

Toolbox for acoustic scene creation and rendering (TASCAR)

Render methods and research applications

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Digital Hearing Devices

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HörTech gGmbH, Oldenburg

9th April, 2015, Linux Audio Conference









Introducing . . .

sensorama

The Revolutionary Motion Picture System
that takes you into another world
with

- 3-D
- WIDE VISION
- MOTION
- COLOR
- STEREO-SOUND
- AROMAS
- WIND



Aug. 28, 1962

M. L. HEILIG

3,050,870

SENSORAMA SIMULATOR

Filed Jan. 10, 1961

8 Sheets-Sheet 3

Fig. 5.

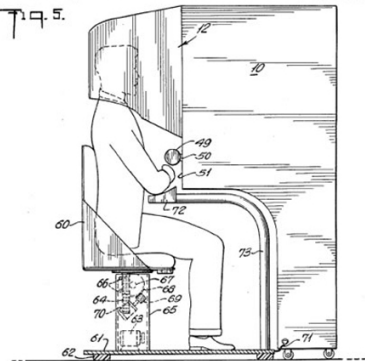
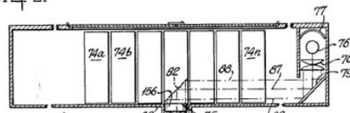


Fig. 6.



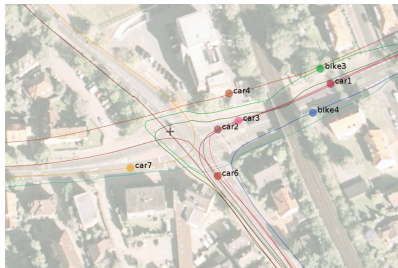




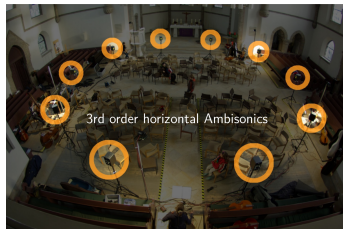
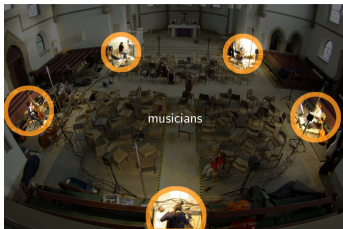
TASCAR

Toolbox for Acoustic Scene Creation And Rendering

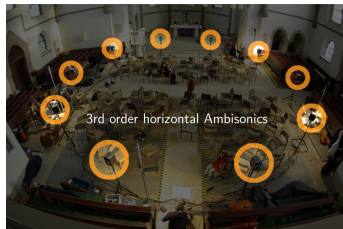
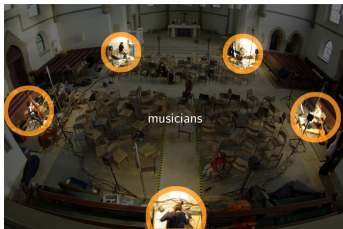
- Linux Software
- Acoustic Environments
- Scenes Design
- Real Time Rendering
- Moving sources, Acoustic modelling
- Interactive



- Initial idea: **Music Performance** (Harmony of the Spheres)
- **Inspiration:** Sound Scape Renderer
- Further development in **Research Project**

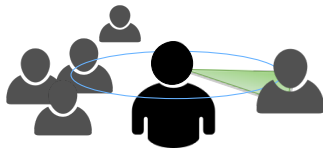
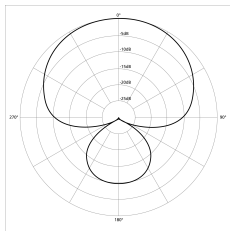


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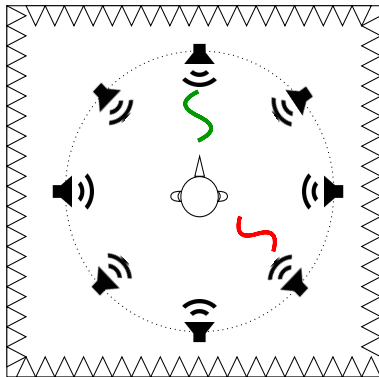


TASCAR in Hearing Research - Motivation?

- Much more than simple amplification
- Space-aware signal processors
- Noise and feedback cancellation
- Directivity patterns, source localisation
- New methods for evaluating spatial properties are needed

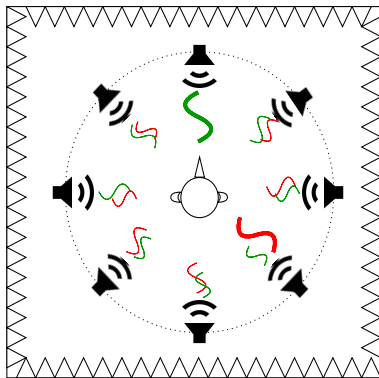


Example : *how directionality in hearing aid improves the speech intelligibility?*



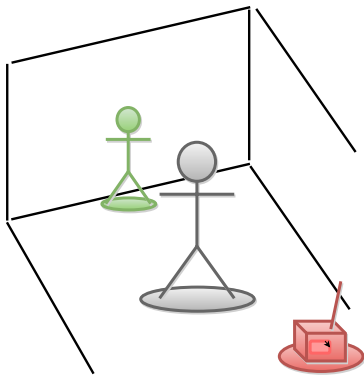
- Typical test set up
- Two separate sources
- For some directions noise can be fully suppressed
- Result: High gain from using directional hearing aid.
- Oversimplification
- Subject behaviour is unnatural
- Unrealistic

Example : *how directionality in hearing aid improves the speech intelligibility?*



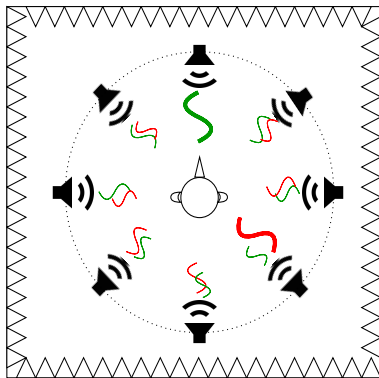
- simulation of an acoustic environment
- all channels active - reflections, reverberation
- much more realistic
- moving sources
- Result: Benefit from using directional hearing aid is not that big anymore
- Results correspond to the real-life situation

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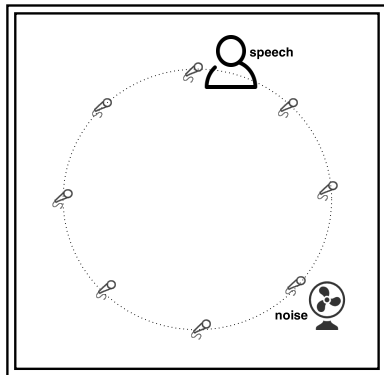


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- Realistic, but...
- not scalable
- uncontrollable
- costs time and effort

Large discrepancies between laboratory and real-life conditions!

■ **Need:**

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■ **Need:**

- *complex, realistic*
- *controllable and reproducible* test environments

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- create a virtual acoustic environment using TASCAR
- play back using loudspeaker array

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Bring the real life into the lab!

Audio content

sound files or real-time audio

Geometry

dynamic objects, image source positions

Acoustic model

transmission and reflection model, rendering to output format

Built upon jack audio connection kit:

Audio content

sound files or real-time audio

Geometry

dynamic objects, image source positions

Acoustic model

transmission and reflection model, rendering to output format

jack ports

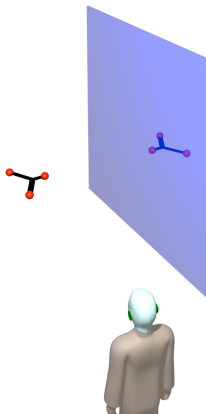
jack time line

- Built from one or more “sound vertices”
- Each sound vertex is omni-directional radiator
- Each sound vertex is a jack input port

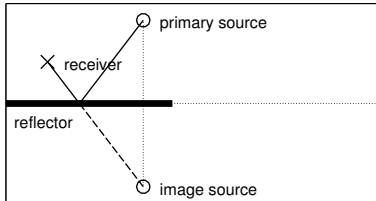


- Encode direction into audio signal
- jack output ports
- Various output formats:
 - omni and cardioid virtual microphones
 - 3rd order ambisonics, horizontal and full-periphonic
 - Horizontal ambisonic panning, arbitrary order, 'basic' and 'in-phase'
- Binaural rendering with virtual loudspeakers and head-related transfer functions
- Reproduction methods validated with different classes of hearing aid algorithms.

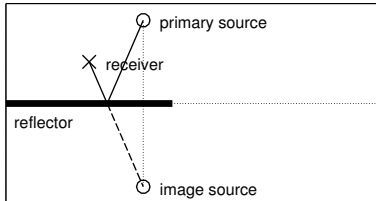
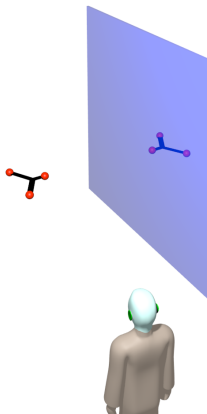


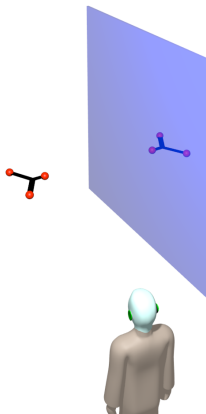


- Polygon-mesh reflectors, dynamic location and orientation
- Surface properties approximated by 1st order low-pass filter
- Time-domain processing:
no pre-calculation of impulse responses
- Soft fades at reflector boundaries:

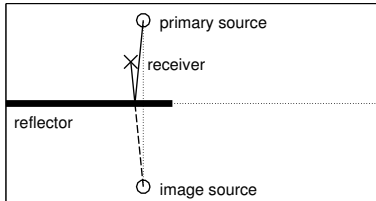


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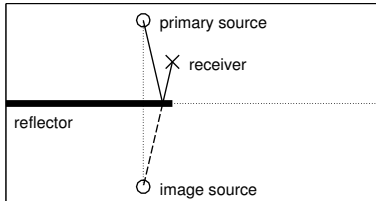
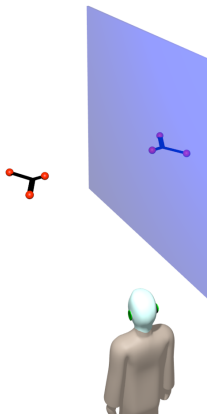




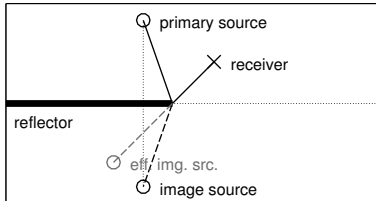
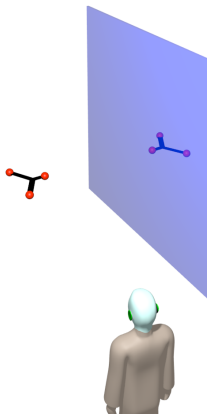
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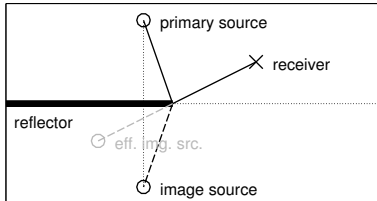
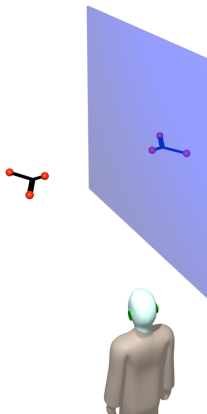
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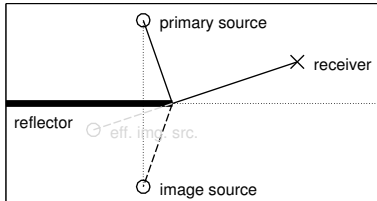
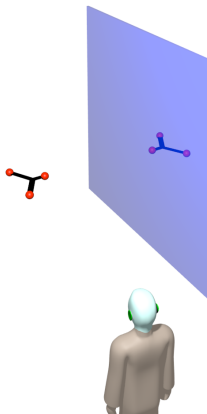
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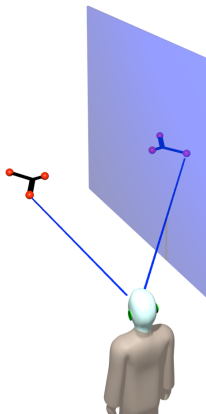


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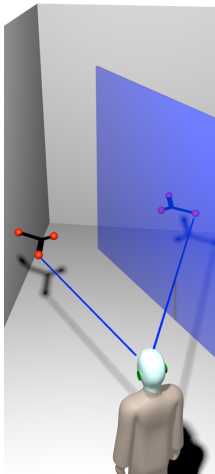


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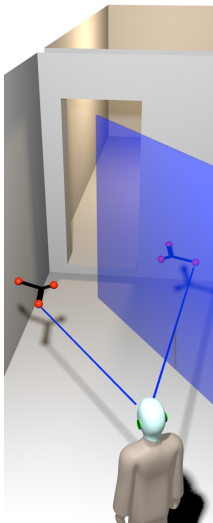


- Time variant delay line
 - Delay line for each image source
 - Doppler shift for fast movements
 - Time varying comb filter effects for slow movements
- Air absorption model
 - Simplification: 1st order low-pass with distance-dependent filter coefficients
 - Good match up to 100 m
 - 18°C, 60% rel. humidity

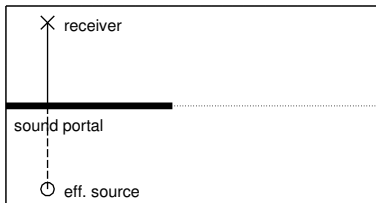


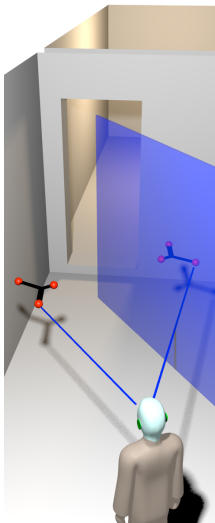
- Allow to split large scenes into sub-spaces
- Zero-gain if receiver is within (“inner” masks) or outside (“outer” masks) masks
- Soft boundaries, von-Hann ramp



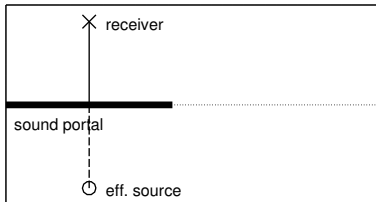


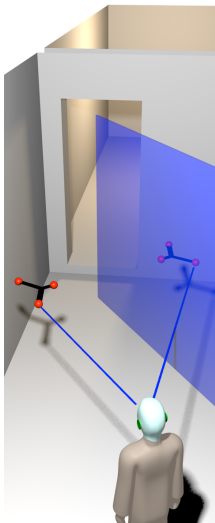
- Sound portals = dedicated sound sources
- Input: output of microphone in adjacent room
- Rectangular area, always radiating from closest point to receiver
- Increased effective distance to avoid proximity effect



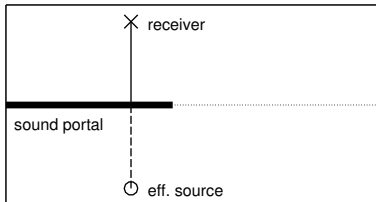


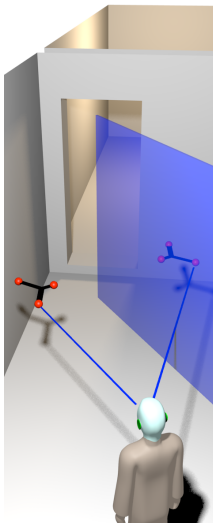
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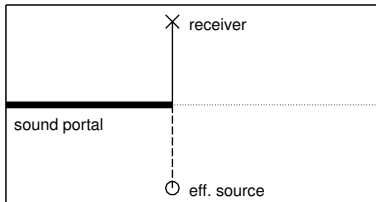


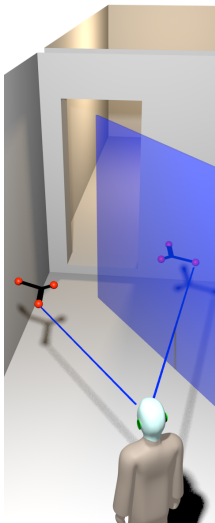
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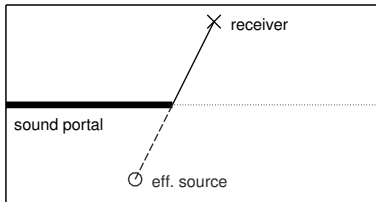


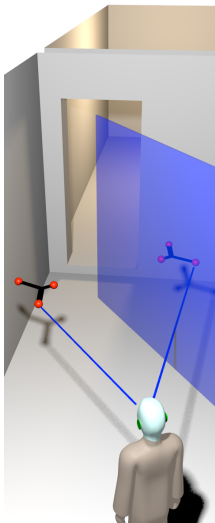
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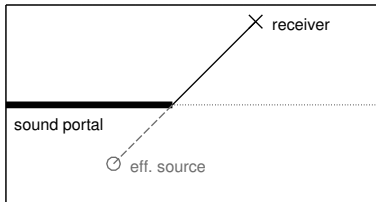


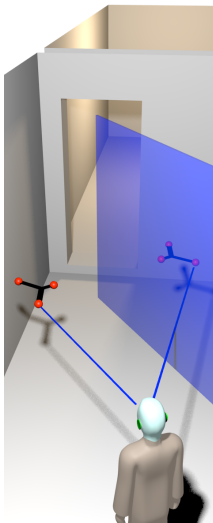
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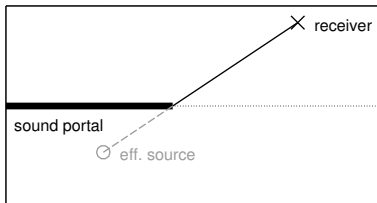


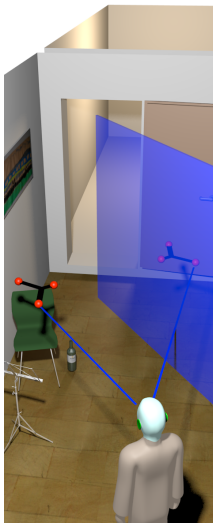
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- First order ambisonics (FOA) recordings for diffuse background sounds
- Diffuse reverberation in first order ambisonics with external tools:
 - Convolution reverb
 - Feedback delay networks
- No transmission model:
 - Constant gain
 - No Doppler shift
- Requires FOA decoder for each receiver type

- **Trajectories**
defined by sampled *location* and *orientation*
- **Delta transforms**
controlled via OSC or geometry modifier plugins
- Updated on each processing cycle
- Derived parameters interpolated within processing blocks
- All objects can be dynamic:
sources, receivers, reflectors, volume masks

TASCAR is *not* a room acoustic simulator

- Simplifications of reflections and sound propagation:
 - Missing/simplified diffraction model
 - Missing absorbers and obstacles
- Real-time processing limits complexity

TASCAR is *not* a room acoustic simulator

Motion blurs and displaces sources

- Linear interpolation of panning coefficients, e.g., ambisonics weights, within blocks
- Acoustic travel time not taken into account in trajectory processing

TASCAR is *not* a room acoustic simulator

Motion blurs and displaces sources

Acoustic artifacts

- Delay lines use nearest neighbor interpolation
- Reproduction methods may not create correct physical sound field

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Acoustic artifacts

Huge code base

- Undiscovered bugs are likely

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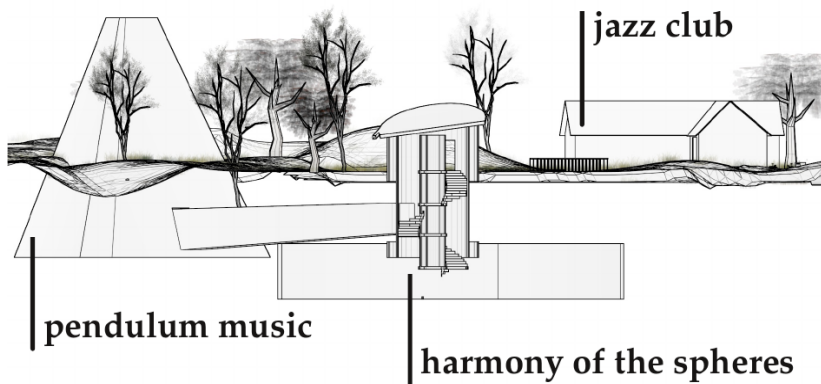
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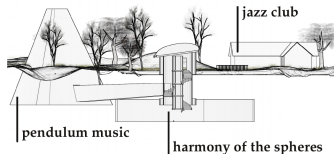
Huge code base

Transparent system:

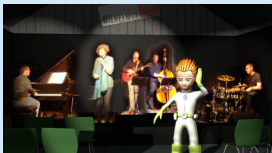
- Impact on research applications is continuously assessed.
- Awareness of limitations is shared with users.

- Interactive virtual acoustic environment
- Coupling to computer graphics (blender game engine):
 - Game logic processing:
blender → TASCAR (e.g., receiver position)
 - Visual representation:
TASCAR → blender (e.g., generated positions)
- Demonstrating all described aspects of TASCAR





jazz club



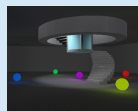
Explore the stage
and room acoustics

pendulum music



Dynamic feedback
loop simulation

harmony of the spheres



Doppler shift and
distance perception

- Today 15:30 (Installation space):
Hands-on workshop, 8 channel loudspeaker reproduction
- Saturday 11:30 (poster session, Foyer):
Play and learn, headphone system
- Any other time:
Ask Joanna or Giso

- **Universität Oldenburg:**

- Core development

- Open source; undocumented but functional

- <https://github.com/gisogrimm/tascar>

- **HörTech gGmbH:**

- Maintenance and support

- User interfaces, data logging, customization

- Commercial license or project participation

- <http://www.hoertech.de/>

- Tool for rendering dynamic spatially complex acoustic environments
- Include movement of sources and listeners
- Full control, scalable and reproducible
- Focus on plausibility and basic acoustic properties for hearing aid research

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Outlook

- Diffraction model, directional sources

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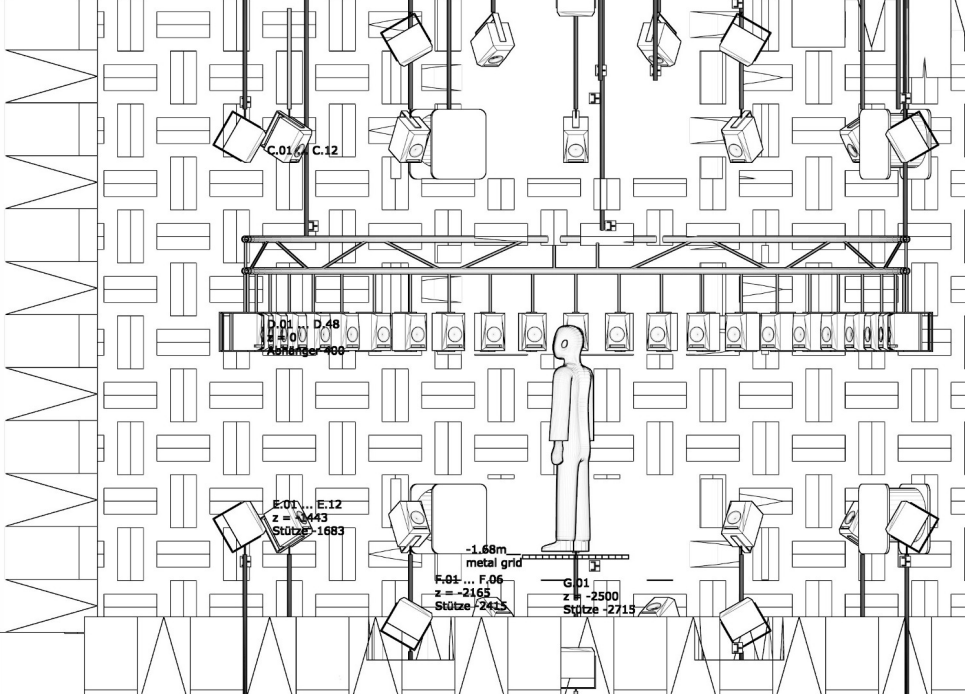
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- Many more TASCAR-based studies in hearing aid research

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Outlook

- Diffraction model, directional sources
- Many more TASCAR-based studies in hearing aid research
- Large VR lab in Oldenburg, powered by TASCAR



Thank you for your attention!

- #1:** Space-aware hearing aids and head motion
(PhD project Maartje Hendrikse)
- #2:** The Influence of Dynamic Binaural Cues on Speech
Intelligibility
(Diploma thesis Jan Heeren)
- #3:** Spatial dynamics and postural stability
(Bachelor thesis Isabel Büsing)

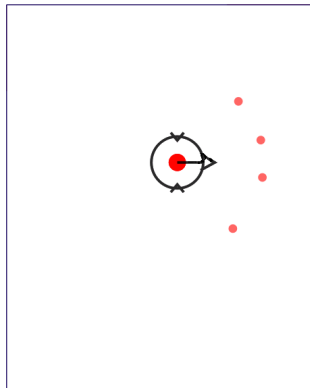
Example 1: Space-aware hearing aids and head motion

- Can we identify individual head movement strategies?
- Are individual head movement strategies task dependent?
- Will hearing aid performance be affected?
- Apparatus:
 - 8 channel loudspeaker array
 - 9 DOF wireless head motion sensor
 - 'kinect' depth camera (skeleton tracker)
 - Electro-oculography (gaze direction)

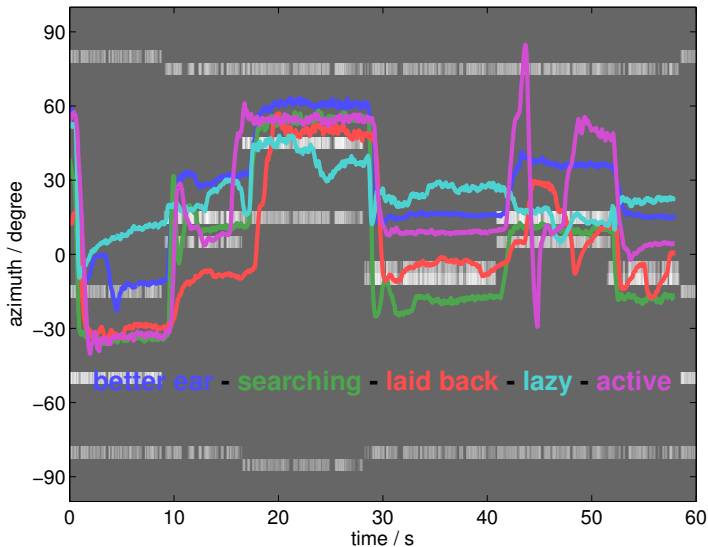
Work in progress, preliminary data.

Example 1: Space-aware hearing aids and head motion

- Panel discussion
- Early reflections
- Task:
Carefully listen to the
discussion.
- Recording of head
orientation

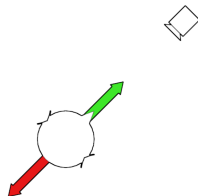


Example 1: Space-aware hearing aids and head motion



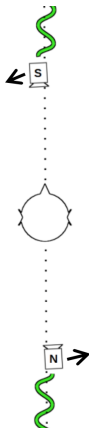
Example 2: “The Influence of Dynamic Binaural Cues on Speech Intelligibility”

- **Binaurally ambiguous listening positions** - Small binaural cues like ITD or ILD
- **Assumption:** Dynamic cues e.g. minimal head or source movements contribute to a better spatial resolution in complex listening situations.
 - Better localisation
 - Better speech intelligibility



- *What is the effect of the dynamic binaural cues?*
 - measuring SRT in dynamic conditions

Example 2: “The Influence of Dynamic Bin-aural Cues on Speech Intelligibility”



Rotational



Counter-rotational

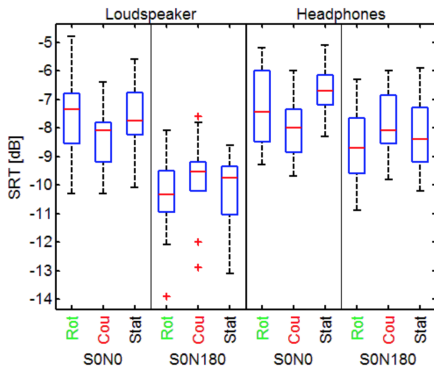


Static

Example 2: “The Influence of Dynamic Binaural Cues on Speech Intelligibility”

Hypotheses proved:

- Speech intelligibility increases if sources move towards different ears (Rot by S0N180 and Cou by S0N0)
- Speech intelligibility decreases if sources move towards the same ear (Cou by S0N180 and Rot by S0N180)



Example 3: Spatial dynamics and postural stability

Context Some HA users feel disturbed by fast-acting automatics

Literature Static acoustic information supports sense of balance

Goal Explore impact of spatially dynamic acoustic information

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Goal Explore impact of spatially dynamic acoustic information

Test conditions

- 10 young participants with normal vision and hearing
- Task (clinical): “Fukuda Stepping Test”
- Test setup: TASCAR with Kinect camera
- Three control parameters:

Complexity	Dynamics	Vision
simple	static	eyes open
complex	dynamic	eyes closed

Example 3: Spatial dynamics and postural stability

